

```
In[1]:= ClearAll["Global`*"]
```

```
(*Probabilities of selection for the case sR is played and for the case sL*)
```

```
pR[sR_] = 1 / 2 + sR;
```

```
pL[sL_] = 1 / 2 + sL;
```

```
(*We compute the continuation values for strategies (sL, sR, xL, xR)*)
```

```
(* We use the following notation for the policies: we consider x_i,  
the "concession" of an agent i,  
hence L's policy y_L= 0 + x_L and R's policy y_R= 1 - x_R*)
```

```
U = Solve[
```

```
  wLl == (1 - pL[sL]) * (b - xL + beta * wLl) + pL[sL] * (- (1 - xR) + beta * wLr) &&
```

```
  wLr == (1 - pR[sR]) * (b - xL + beta * wLl) + pR[sR] * (- (1 - xR) + beta * wLr) &&
```

```
  wRl == (1 - pL[sL]) * (- (1 - xL) + beta * wRl) + pL[sL] * (b - xR + beta * wRr) &&
```

```
  wRr == (1 - pR[sR]) * (- (1 - xL) + beta * wRl) + pR[sR] * (b - xR + beta * wRr) &&
```

```
  wPl ==
```

```
    (1 - pL[sL]) * (- (theta - xL) + beta * wPl) + pL[sL] * (- (1 - xR - theta) + beta * wPr) &&
```

```
  wPr == (1 - pR[sR]) * (- (theta - xL) + beta * wPl) +
```

```
    pR[sR] * (- (1 - xR - theta) + beta * wPr), {wLl, wLr, wRl, wRr, wPl, wPr}];
```

```
(*R's continuation value when R was selected last*)
```

```
wRr[beta_, b_, sL_, sR_, xL_, xR_] = FullSimplify[wRr /. U[[1]]];
```

```
(*L's continuation value when L was selected last*)
```

```
wLl[beta_, b_, sL_, sR_, xL_, xR_] = FullSimplify[wLl /. U[[1]]];
```

```
(*Principal's continuation value when L was selected last*)
```

```
wPl[beta_, b_, theta_, sL_, sR_, xL_, xR_] = FullSimplify[wPl /. U[[1]]];
```

```
(*Principal's continuation value when R was selected last*)
```

```
wPr[beta_, b_, theta_, sL_, sR_, xL_, xR_] = FullSimplify[wPr /. U[[1]]];
```

```
(**Principal's and R's punishment**)
```

```
alphaR[m_, beta_, b_] = FullSimplify[With[{xL = 0},
```

```
  With[{xR = 0}, With[{sL = -m}, With[{sR = -m}, wRr[beta, b, sL, sR, xL, xR]]]]]
```

```
alphaP[m_, beta_, b_, theta_] = FullSimplify[With[{xL = 0},
```

```
  With[{xR = 0}, With[{sL = -m}, With[{sR = -m}, wPl[beta, b, theta, sL, sR, xL, xR]]]]]
```

```
(*At the end of the code we show this is the right punishment  
for the Principal in the region we are interested in here*)
```

$$\frac{1 - b + 2 (1 + b) m}{2 (-1 + \text{beta})}$$

```
Out[9]=
```

Out[10]=

$$\frac{1 + m (-2 + 4 \text{theta})}{2 (-1 + \text{beta})}$$

In[11]:= (**Agent's enforcement constraints**)

```

enforcementLmax[m_, beta_, b_, sL_, sR_, xL_, xR_, alphaL_] =
  FullSimplify[xL + beta * (alphaL - wL1) /. U[[1]]];
enforcementRmax[m_, beta_, b_, sL_, sR_, xL_, xR_] =
  FullSimplify[xR + beta * (alphaR[m, beta, b] - wRr) /. U[[1]]];

```

```

In[13]:= (**R' Actions in the Optimal contract**)
(*Optimal contract -- Solving R's enforcement constraints*)

```

```

enforcementRmaxsubstituted[m_, beta_, b_, xL_, xR_] = FullSimplify[
  With[{sR = m}, With[{sL = -m}, enforcementRmax[m, beta, b, sL, sR, xL, xR]]]]
solvexR = FullSimplify[Solve[enforcementRmaxsubstituted[m, beta, b, xL, xR] == 0, xR]]
xRmax[m_, beta_, b_, xL_] = FullSimplify[xR /. solvexR[[1]]];

```

Out[13]=

$$\frac{2 (1 + b) \text{beta} m (-2 + \text{beta} + 2 \text{beta} m) + \text{beta} (-1 + 2 m) xL - (-2 + \text{beta} + 2 \text{beta} m) xR}{2 (-1 + \text{beta}) (-1 + 2 \text{beta} m)}$$

Out[14]=

$$\left\{ \left\{ xR \rightarrow 2 (1 + b) \text{beta} m + \frac{\text{beta} (-1 + 2 m) xL}{-2 + \text{beta} + 2 \text{beta} m} \right\} \right\}$$

In[16]:= (**L' Punishment -- P's continuation value at the back-to-business phase**)

```

Carrot[m_, beta_, b_, theta_, xL_] =
  FullSimplify[With[{xR = xRmax[m, beta, b, xL]}, With[{sR = m},
    With[{sL = -m}, -(theta - xL) + beta * wPl[beta, b, theta, sL, sR, xL, xR]]]]]

```

Out[16]=

$$\frac{((-2 + \text{beta} + 2 \text{beta} m) (-\text{beta} (-1 + 2 m) (-1 + 2 (1 + b) \text{beta} m) + 2 (-1 + \text{beta}) \text{theta}) - 2 (2 + \text{beta} (-2 + \text{beta} - 4 m + 4 \text{beta} m^2)) xL}{(2 (-1 + \text{beta}) (-1 + 2 \text{beta} m) (-2 + \text{beta} + 2 \text{beta} m))}$$

```
In[17]:= (**L' Punishment -- P's continuation value at punishment phase**)
```

```
Stickprevious[m_, beta_, b_, theta_, xL_, xR_, Stick_] = FullSimplify[With[{sR = m},
  (1 - pR[sR]) * Carrot[m, beta, b, theta, xL] + pR[sR] * (- (1 - xR - theta) + beta * Stick) ] ]
sticksolve1 = Solve[Stick == Stickprevious[m, beta, b, theta, xL, xR, Stick], Stick]
Stick[m_, beta_, b_, theta_, xL_, xR_] = FullSimplify[Stick /. sticksolve1[[1]]];
(*Now we can solve for R's concession in the punishment phase of L's Punishment*)
```

```
sticksolve2 =
```

```
FullSimplify[Solve[Stick[m, beta, b, theta, xL, xR] == alphaP[m, beta, b, theta], xR]]
xRstick[m_, beta_, b_, theta_, xL_] = FullSimplify[xR /. sticksolve2[[1]]];
```

```
Out[17]=
```

$$\left((-1 + 2m) \left((-2 + \beta + 2\beta m) (\beta (-1 + 2m) (-1 + 2(1 + \beta)\beta m) - 2(-1 + \beta)\theta) + 2(2 + \beta(-2 + \beta - 4m + 4\beta m^2)) xL \right) \right) /$$

$$(4(-1 + \beta)(-1 + 2\beta m)(-2 + \beta + 2\beta m)) + \left(\frac{1}{2} + m \right)$$

$$(-1 + \beta \text{Stick} + \theta + xR)$$

```
Out[18]=
```

$$\left\{ \left\{ \text{Stick} \rightarrow \frac{1}{1 - \beta \left(\frac{1}{2} + m \right)} \left(-\frac{1}{2} - m + \left(\frac{1}{2} + m \right) \theta + \right. \right.$$

$$\left. \left((-1 + 2m) \left((-2 + \beta + 2\beta m) (\beta (-1 + 2m) (-1 + 2(1 + \beta)\beta m) - 2(-1 + \beta)\theta) + 2(2 + \beta(-2 + \beta - 4m + 4\beta m^2)) xL \right) \right) / \right.$$

$$\left. \left. (4(-1 + \beta)(-1 + 2\beta m)(-2 + \beta + 2\beta m)) + \left(\frac{1}{2} + m \right) xR \right) \right\} \right\}$$

```
Out[20]=
```

$$\left\{ \left\{ xR \rightarrow \left(m(-2 + \beta + 2\beta m) (4 - 8\theta + \right. \right.$$

$$\left. \beta(-4 - \beta\beta(1 - 2m)^2 + 8(-1 + \beta)m - 2(1 + 2m)(-4 + \beta + 2\beta m)\theta) \right) - \right.$$

$$\left. (-1 + 2m) (2 + \beta(-2 + \beta - 4m + 4\beta m^2)) xL \right) /$$

$$\left. \left. ((-1 + \beta)(1 + 2m)(-1 + 2\beta m)(-2 + \beta + 2\beta m)) \right) \right\} \right\}$$

```

In[22]:= (*Once we have obtained R's concessions in the L's punihsmnt phase,
we can obtain L's punishment*)

(*First, we compute L's punishment value at the start of the back-to-business phase*)

LatCarrot[m_, beta_, b_, xL_] =
  FullSimplify[With[{xR = xRmax[m, beta, b, xL]}, With[{sR = m}, With[{sL = -m},
    b - xL + beta * wL1[beta, b, sL, sR, xL, xR]]]]]

(*Second, we compute L's punishment value at the start of the punishment phase *)

LatStickprevious[m_, beta_, b_, theta_, xL_, LatStick_] =
  FullSimplify[With[{sR = m}, With[{xR = xRstick[m, beta, b, theta, xL]},
    (1 - pR[sR]) * LatCarrot[m, beta, b, xL] + pR[sR] * (- (1 - xR) + beta * LatStick)]]];

sticksolve3 = FullSimplify[
  Solve[LatStick == LatStickprevious[m, beta, b, theta, xL, LatStick], LatStick]]

(*which gives us L's punishment as a function
of L's concessions in the Optimal contract, xL*)

LatStick[m_, beta_, b_, theta_, xL_] = FullSimplify[LatStick /. sticksolve3[[1]]]

```

Out[22]=

$$\frac{b(-2 + \text{beta}) + \text{beta} - 2(1 + b)\text{beta}m}{2(-1 + \text{beta})} + \frac{2xL}{-2 + \text{beta} + 2\text{beta}m}$$

Out[24]=

$$\left\{ \left\{ \text{LatStick} \rightarrow \frac{-1 + b - 2bm - 2xL + 2m(1 + \text{beta} - 4\theta + 2\text{beta}\theta + \text{beta}m(-2 + 4\theta) + 2xL)}{2(-1 + \text{beta})(-1 + 2\text{beta}m)} \right\} \right\}$$

Out[25]=

$$\frac{-1 + b - 2bm - 2xL + 2m(1 + \text{beta} - 4\theta + 2\text{beta}\theta + \text{beta}m(-2 + 4\theta) + 2xL)}{2(-1 + \text{beta})(-1 + 2\text{beta}m)}$$

```

In[26]:= (*Closing the Optimal contract and L's punishment
together -- Finding L's concessions in the Optimal contract, xL*)

enforcementLmaxsubstituted[m_, beta_, b_, theta_, xL_] = FullSimplify[
  With[{alphaL = LatStick[m, beta, b, theta, xL]}, With[{xR = xRmax[m, beta, b, xL]},
    With[{sR = m}, With[{sL = -m}, enforcementLmax[m, beta, b, sL, sR, xL, xR, alphaL]]]]]]

xLmaxsolve =
  FullSimplify[Solve[enforcementLmaxsubstituted[m, beta, b, theta, xL] == 0, xL]]
xLmax[m_, beta_, b_, theta_] = FullSimplify[xL /. xLmaxsolve[[1]]];

```

```

Out[26]=

$$\frac{\text{beta } m (-2 + \text{beta} + 2 \text{beta } m)^2 (b + 2 \text{theta}) + (-2 + \text{beta} (4 + \text{beta} (-1 + 4 (-1 + m) m))) xL}{(-1 + \text{beta}) (-1 + 2 \text{beta } m) (-2 + \text{beta} + 2 \text{beta } m)}$$


```

```

Out[27]=

$$\left\{ \left\{ xL \rightarrow -\frac{\text{beta } m (-2 + \text{beta} + 2 \text{beta } m)^2 (b + 2 \text{theta})}{-2 + \text{beta} (4 + \text{beta} (-1 + 4 (-1 + m) m))} \right\} \right\}$$


```

```

In[29]:= (**Obtaining L's Punishment and the Optimal Contract -- we substitute xL**)

alphaL[m_, beta_, b_, theta_] =
  FullSimplify[With[{xL = xLmax[m, beta, b, theta]}, LatStick[m, beta, b, theta, xL]]];
xRstickFinal[m_, beta_, b_, theta_] =
  FullSimplify[With[{xL = xLmax[m, beta, b, theta]}, xRstick[m, beta, b, theta, xL]]]
xRmaxFinal[m_, beta_, b_, theta_] =
  FullSimplify[With[{xL = xLmax[m, beta, b, theta]}, xRmax[m, beta, b, xL]]]

```

```

Out[30]=

$$\frac{(4 m (-2 + 4 \text{theta} + \text{beta} (4 + b (-1 + 2 m) (-1 + 2 \text{beta } m) - 6 \text{theta} - 4 m \text{theta} + \text{beta} (-1 + 2 \text{theta} + 4 m (-1 + m + \text{theta}))))}{((1 + 2 m) (-2 + \text{beta} (4 + \text{beta} (-1 + 4 (-1 + m) m)))}$$


```

```

Out[31]=

$$\text{beta } m \left( 2 (1 + b) - \frac{\text{beta} (-1 + 2 m) (-2 + \text{beta} + 2 \text{beta } m) (b + 2 \text{theta})}{-2 + \text{beta} (4 + \text{beta} (-1 + 4 (-1 + m) m))} \right)$$


```

```
In[32]:= (**REGIONS -- Proof of PROPOSITIONS 4 AND 5**)
```

```
(* When are we at the commitment punishment? -- We obtain a threshold in theta *)
```

```
FullSimplify[D[xRstickFinal[m, beta, b, theta], theta]]
```

```
(*monotone decreasing in theta*)
```

```
solvetheta1 = FullSimplify[Solve[xRstickFinal[m, beta, b, theta] == 0, theta]]
```

```
thetaOutofCommitmentOptimal[m_, beta_, b_] = FullSimplify[theta /. solvetheta1[[1]]];
```

```
(*We now show Proposition 4, the Optimal contract results hold for some theta < 1/2*)
```

```
Reduce[thetaOutofCommitmentOptimal[m, beta, b] >= 1/2 && 0 < beta < 1 && 0 < m < 1/2 && b > 0]
```

```
Out[32]=
```

$$\frac{8(-1 + \beta)m(-2 + \beta + 2\beta m)}{(1 + 2m)(-2 + \beta(4 + \beta(-1 + 4(-1 + m)m)))}$$

```
Out[33]=
```

$$\left\{ \left\{ \theta \rightarrow \frac{2 + \beta(-4 - b + \beta + 2(b + (2 + b)\beta)m - 4(1 + b)\beta m^2)}{2(-1 + \beta)(-2 + \beta + 2\beta m)} \right\} \right\}$$

```
Out[35]=
```

```
False
```

```
In[36]:= (*We can instead show our results with  
respect to b -- we obtain bBar from Proposition 3*)
```

```
solvebBar = FullSimplify[Solve[xRstickFinal[m, beta, b, theta] == 0, b]]
```

```
bBar[m_, beta_, theta_] = FullSimplify[b /. solvebBar[[1]]];
```

```
(*largest b such that punishment without  
concession is possible and commitment=no commitment*)
```

```
Out[36]=
```

$$\left\{ \left\{ b \rightarrow \frac{2 - 4\theta + \beta(-4 + \beta - 2\beta\theta + (6 + 4m)\theta - 4\beta m(-1 + m + \theta))}{\beta(-1 + 2m)(-1 + 2\beta m)} \right\} \right\}$$

```
In[38]:= (*Sanity Check: The calculated should be the same as inverting thetaHat*)
```

```
FullSimplify[
```

```
(b /. Solve[thetaOutofCommitmentOptimal[m, beta, b] == theta, b][[1]]) - bBar[m, beta, theta]]
```

```
Out[38]=
```

```
0
```

```
In[39]:= (*Now we compute \hat{b} from Proposition 5, that is,
the largest b such that P's on-path constraint is redundant*)
solvebHat =
  FullSimplify[Solve[xRstickFinal[m, beta, b, theta] == xRmaxFinal[m, beta, b, theta], b]]
bHat[m_, beta_, theta_] = FullSimplify[b /. solvebHat[[1]]];
(*largest b such that P's on-path constraint does not bind*)
```

Out[39]=

$$\left\{ \left\{ b \rightarrow \frac{4 + \beta^2 (2 + 8m(1 + m(-1 + \theta))) - 2\theta + 8\beta(-1 + \theta) - 8\theta}{\beta(4 + \beta(-1 + 4(-2 + m)m))} \right\} \right\}$$

```
In[41]:= (*We want now to compare this threshold with the theta
(overline) at which the contract stops being (DEC,DEC)*)
```

```
(*To that end, we compute L's enforcement constraint in the Commitment-
Optimal contract for the case in which L's concession equals theta*)
```

```
(*Recall that L's punishment value under commitment
is identical to R's punishment value under non-commitment*)
```

```
enforcementLmaxsubstituted[m_, beta_, b_, theta_] =
  FullSimplify[With[{alphaL = alphaR[m, beta, b]},
    With[{xL = theta}, With[{xR = xRmax[m, beta, b, theta]}, With[{sR = m},
      With[{sL = -m}, enforcementLmax[m, beta, b, sL, sR, xL, xR, alphaL]]]]]]];
```

```
solvetheta2 =
  FullSimplify[Solve[enforcementLmaxsubstituted[m, beta, b, theta] == 0, theta]]
thetaoverline[m_, beta_, b_] = FullSimplify[theta /. solvetheta2[[1]]];
```

Out[42]=

$$\left\{ \left\{ \theta \rightarrow \frac{(1 + b)\beta m(-2 + \beta + 2\beta m)}{-1 + \beta} \right\} \right\}$$